

# Case Study - Beyond the Visible - Multispectral & TIR sUAS Minefield Mapping

Lessons Learned from the Successful Deployment of Multispectral & TIR Imaging Over Live Minefields

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Netherlands



**Mobility  
Robotics**



# 1. Introduction



IKMAA

DMA



LMAC



HCND



SESU



Mobility  
Robotics



german  
humanitarian  
assistance

ODYSSEY  
2025



Ministry of Foreign Affairs of the  
Netherlands



Norwegian People's Aid



## 2. Minefield Scenarios

**Obscured by grass/weeds**

**Buried by sand**



### 3. Materials Analysis

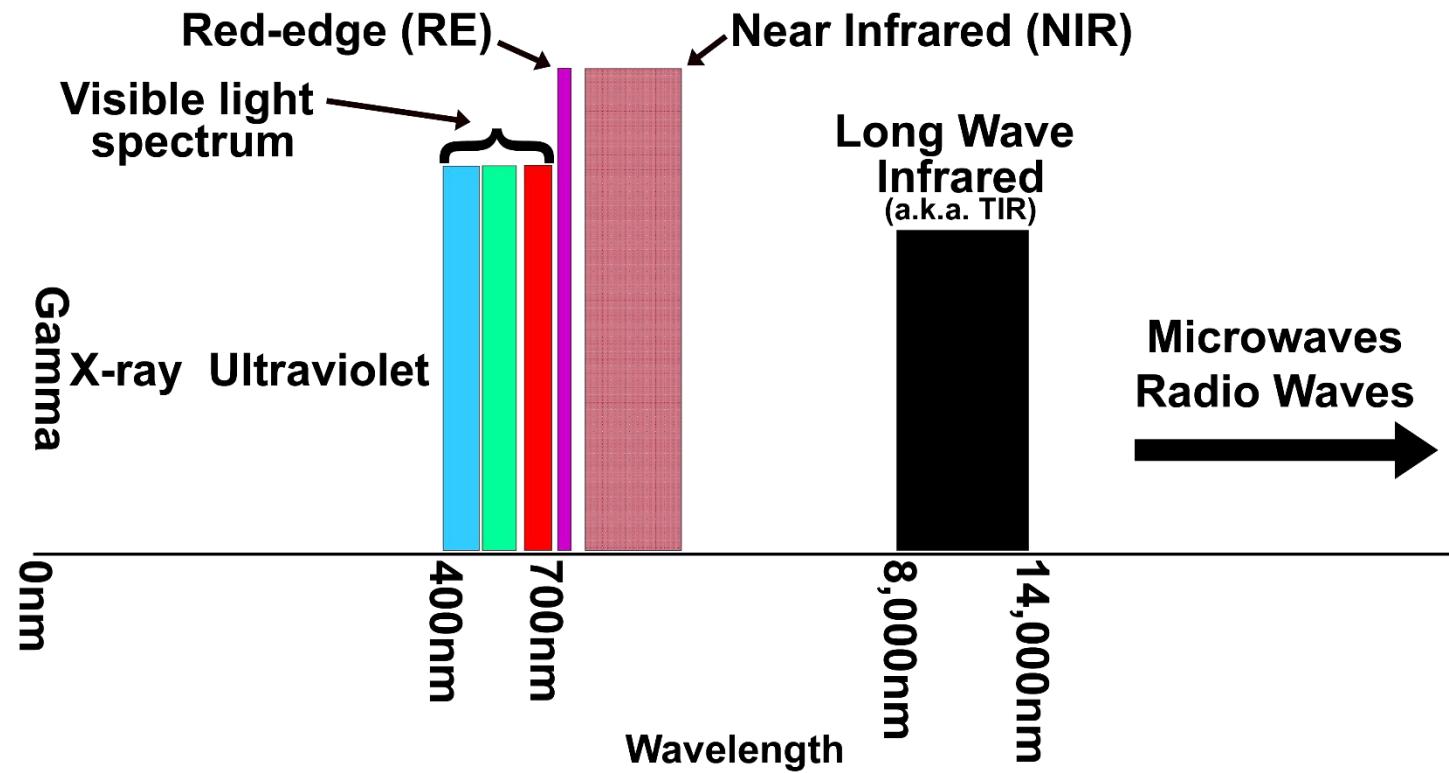
**Metal, plastic, rubber, other materials**

**Colour/pigments**

**Size, shape, distinctive features**

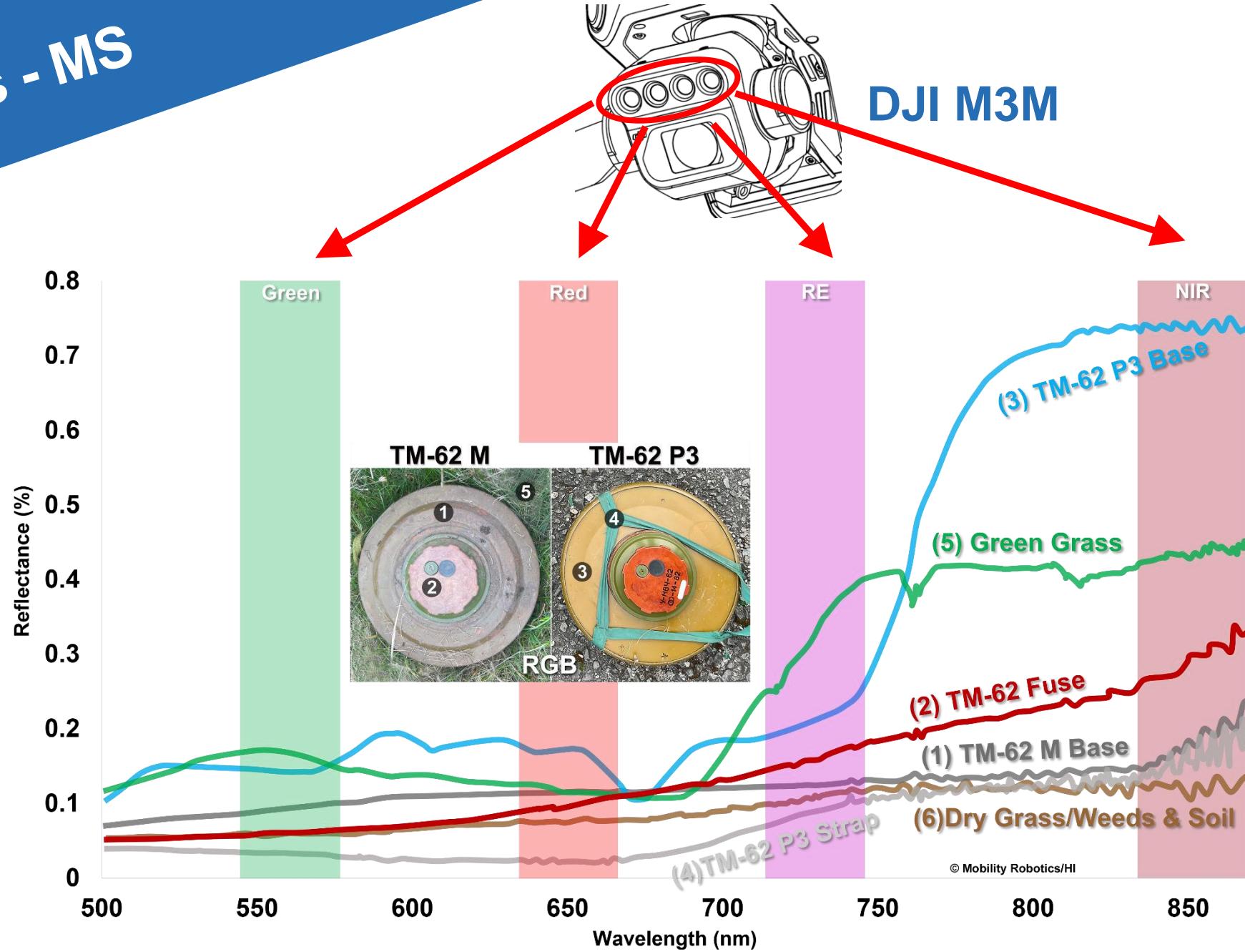


## 4. Sensors – IR

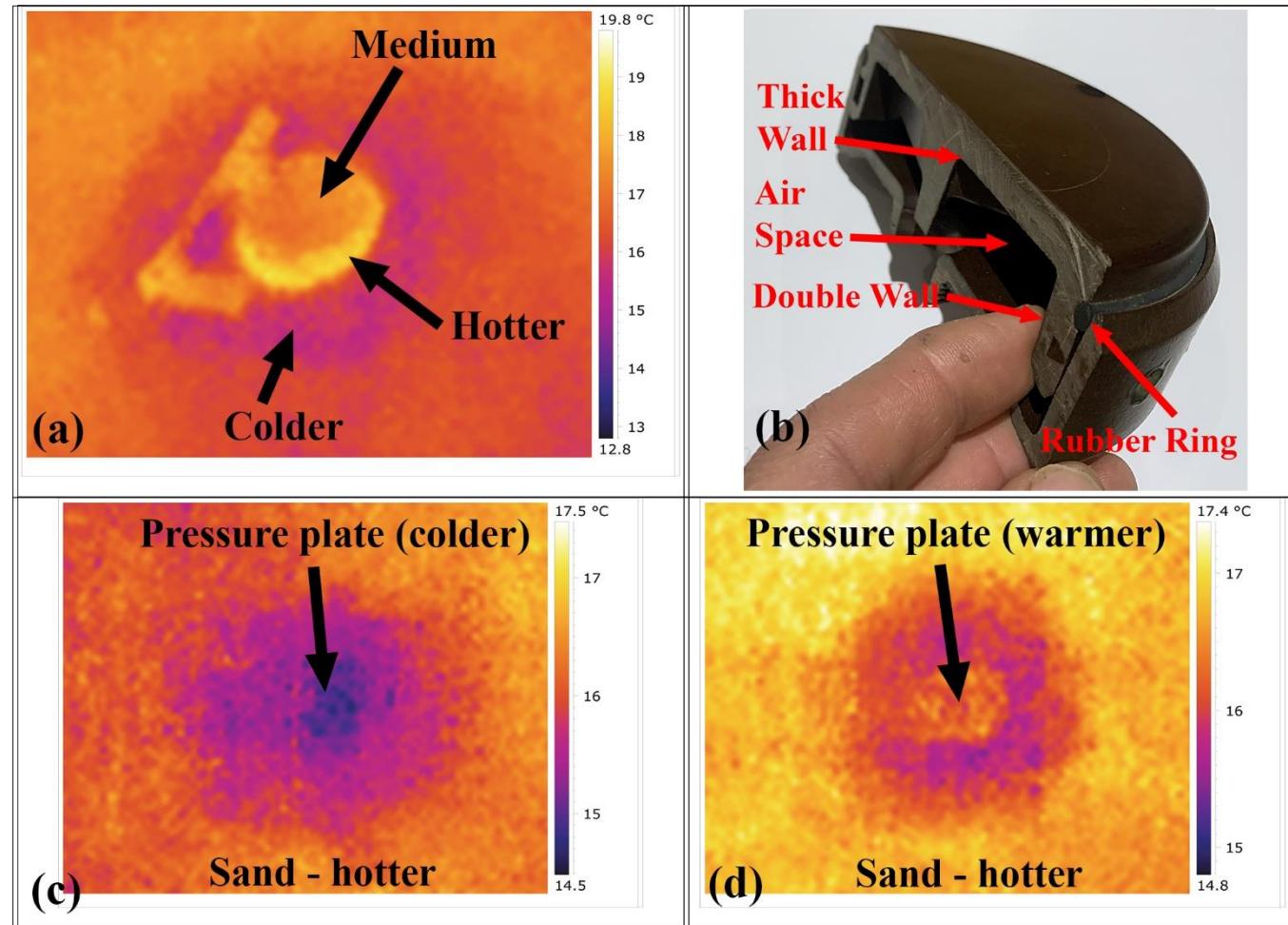


### Differences in NIR & TIR

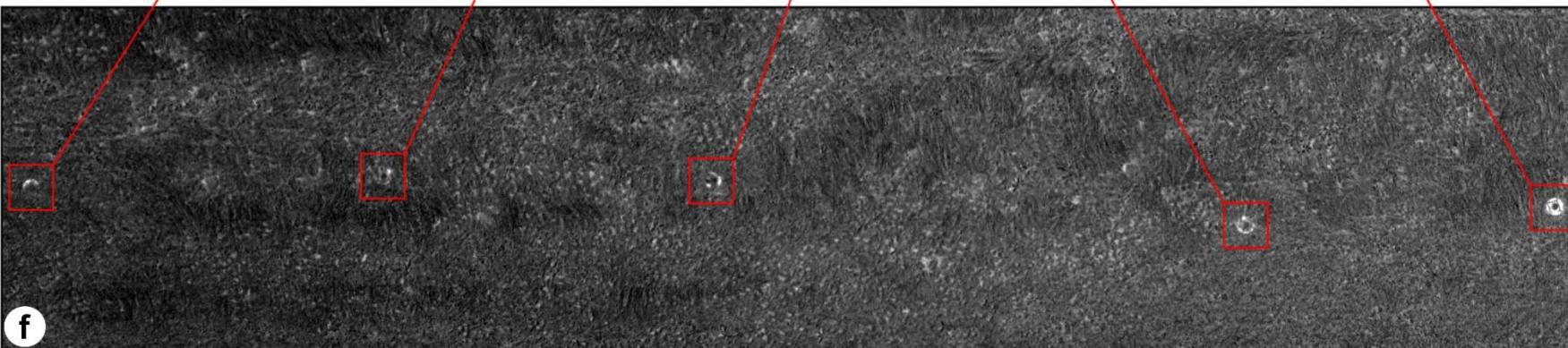
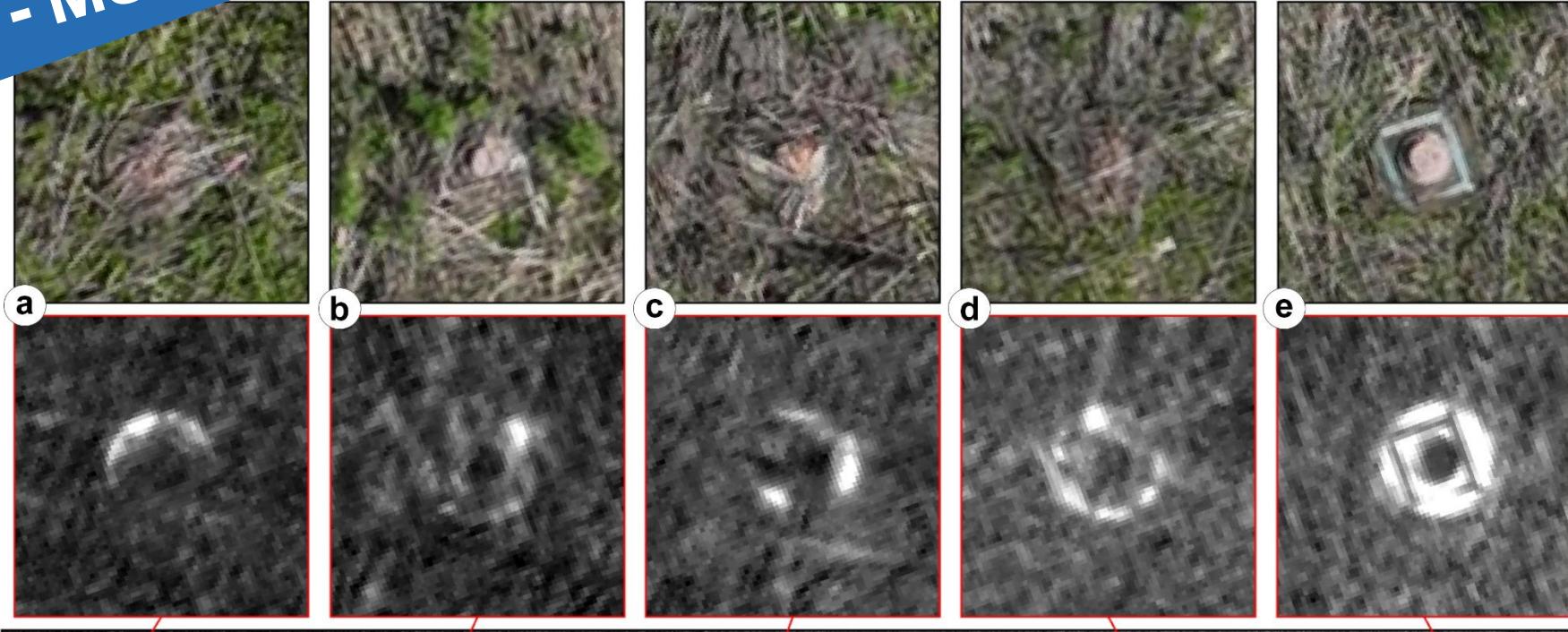
## 5. Sensors - MS



# 6. Sensors - TIR



## 7. Real World Signatures - MS

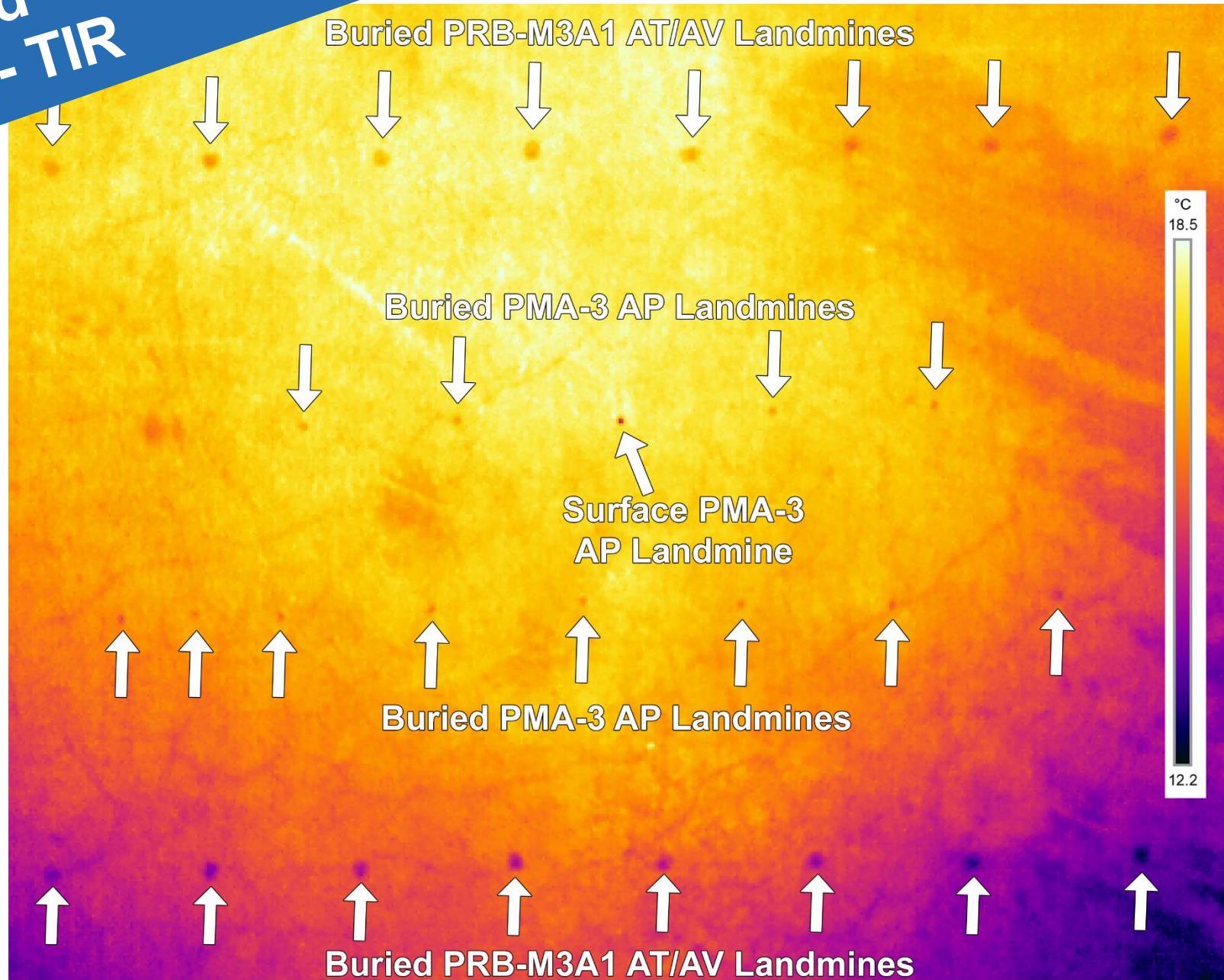


Metres  
0 1.25 2.5 5 7.5 10

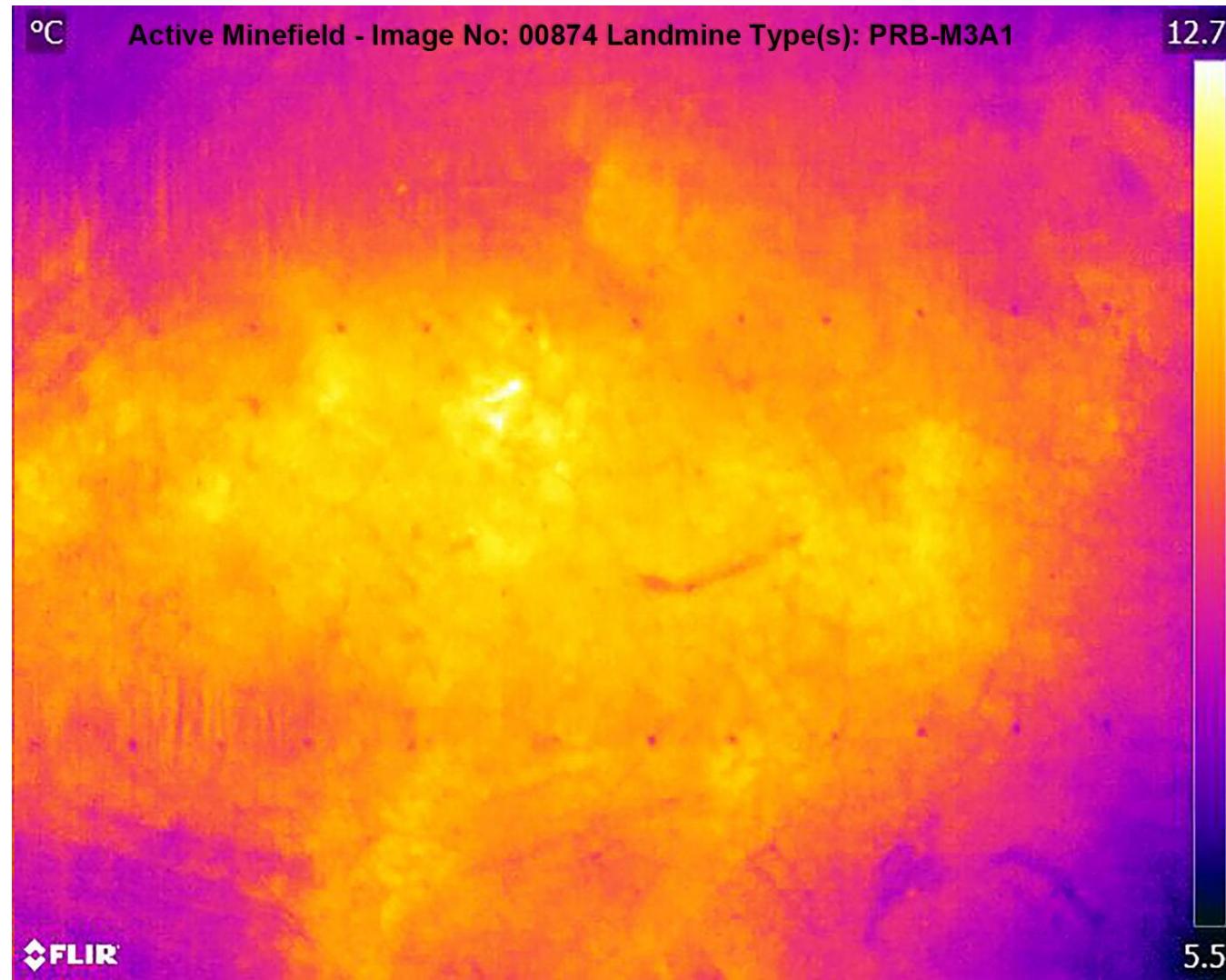


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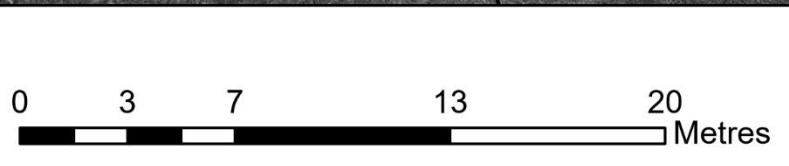
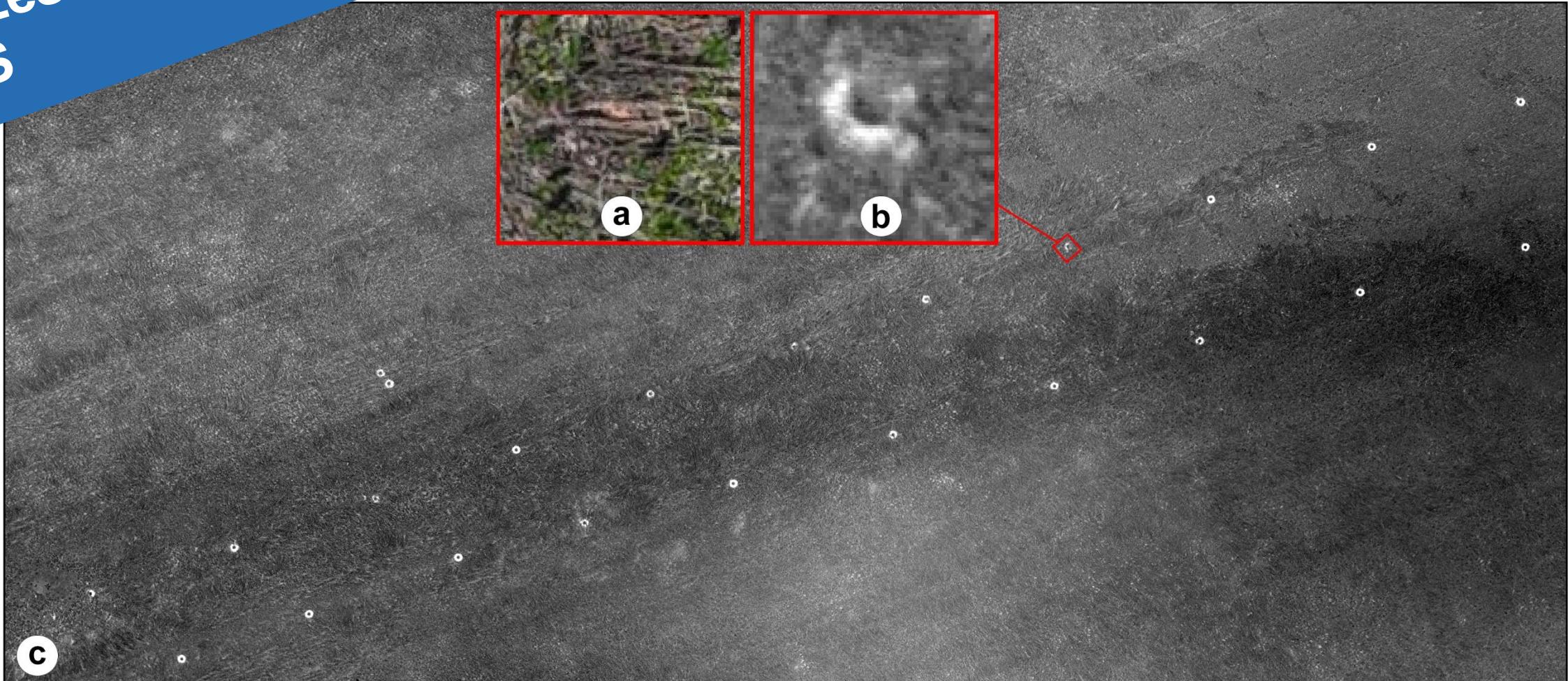
## 8. Real World Signatures - TIR



## 8. Real World Signatures - TIR

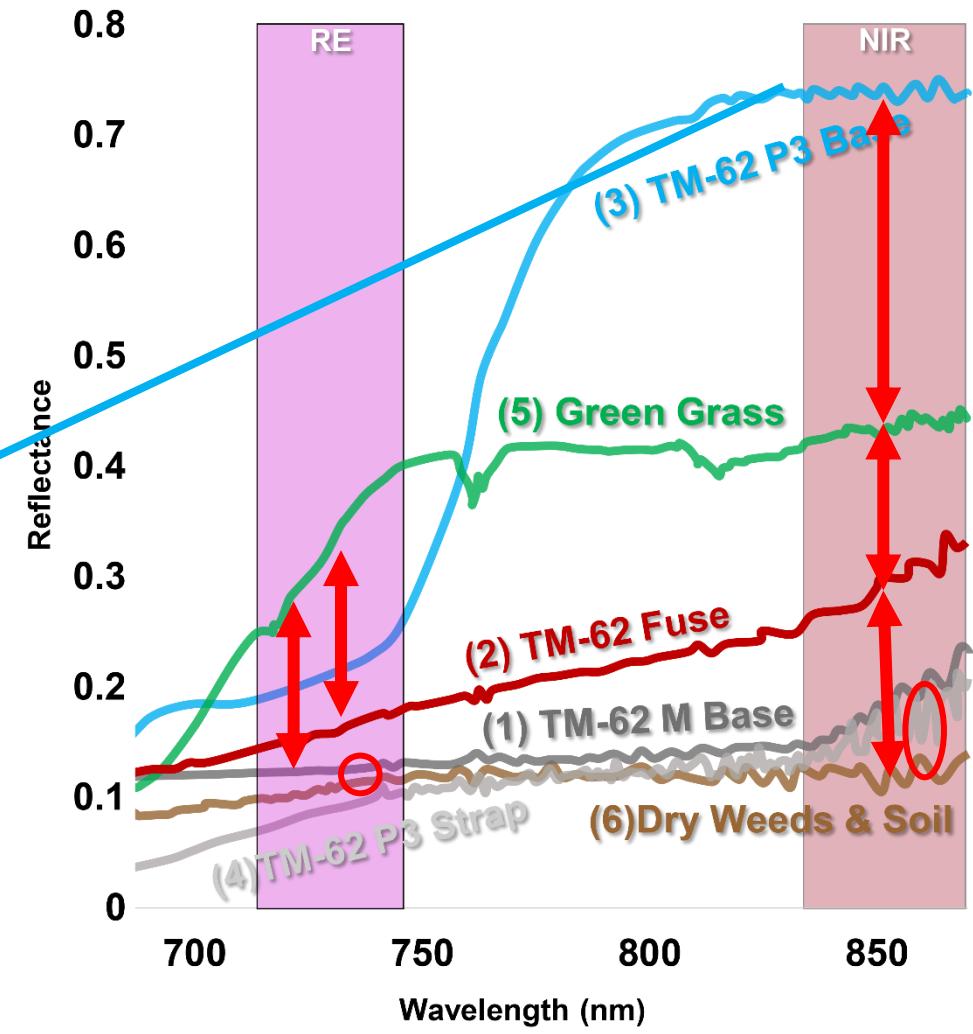
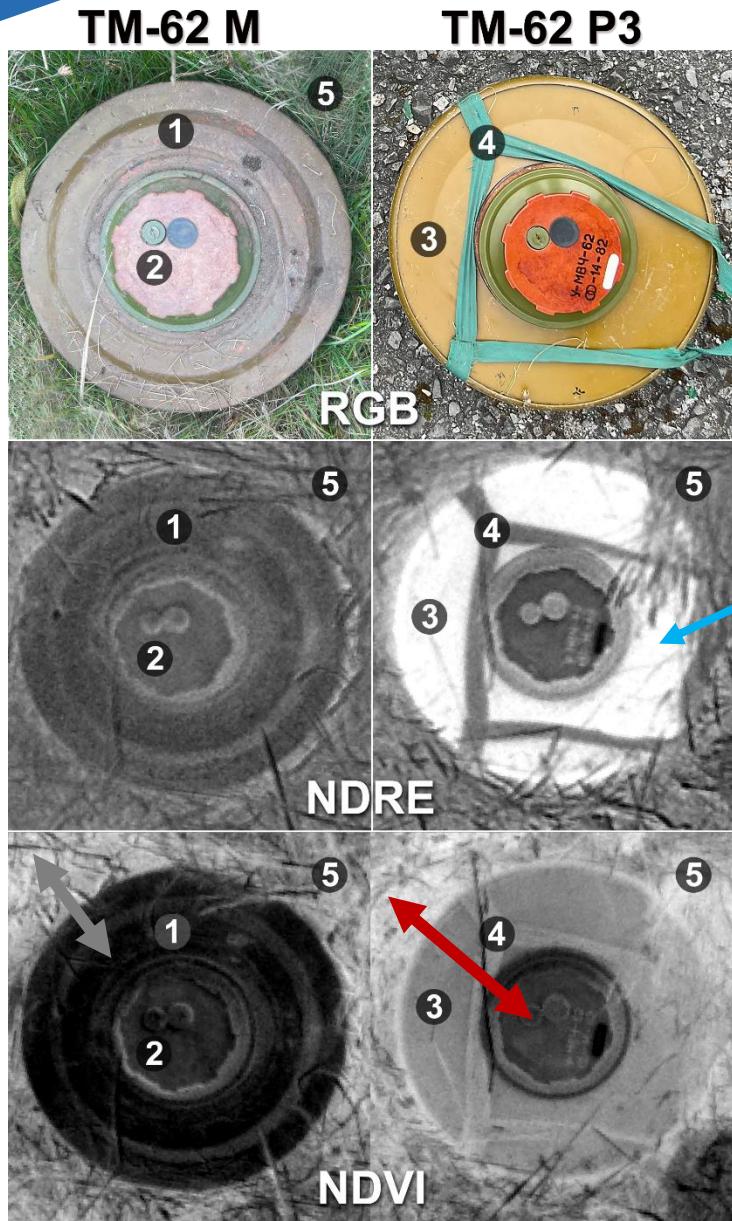


# 9. Lessons Learned - MS



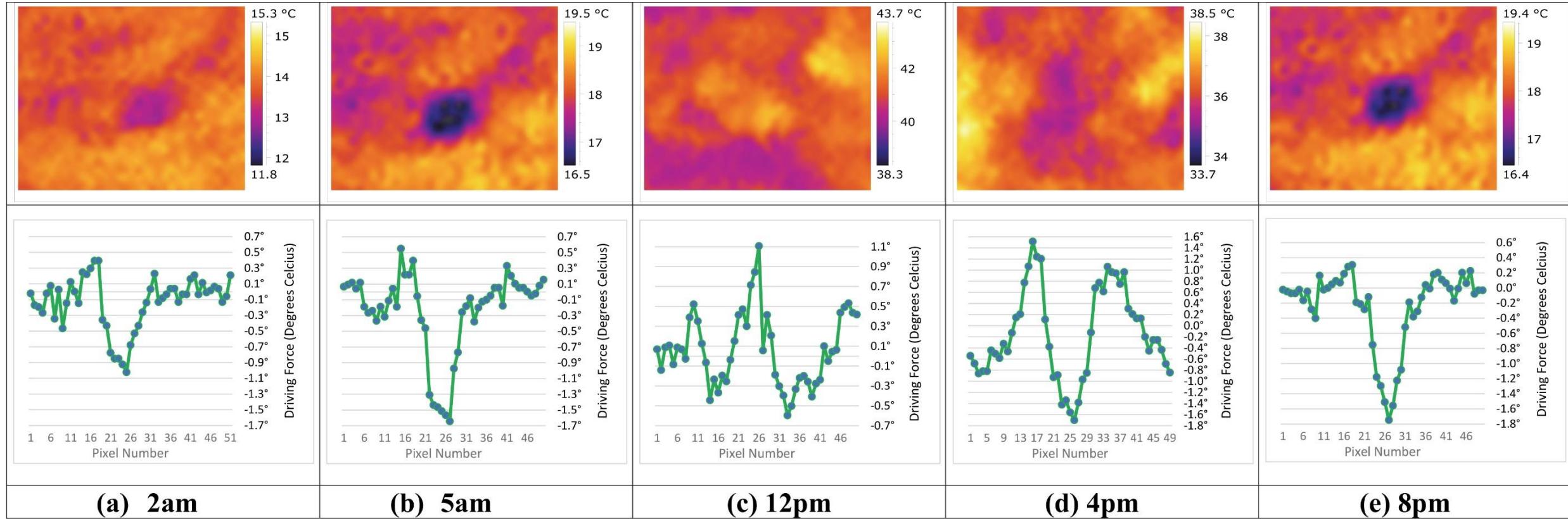
**Mobility Robotics**

# 9. Lessons Learned - MS



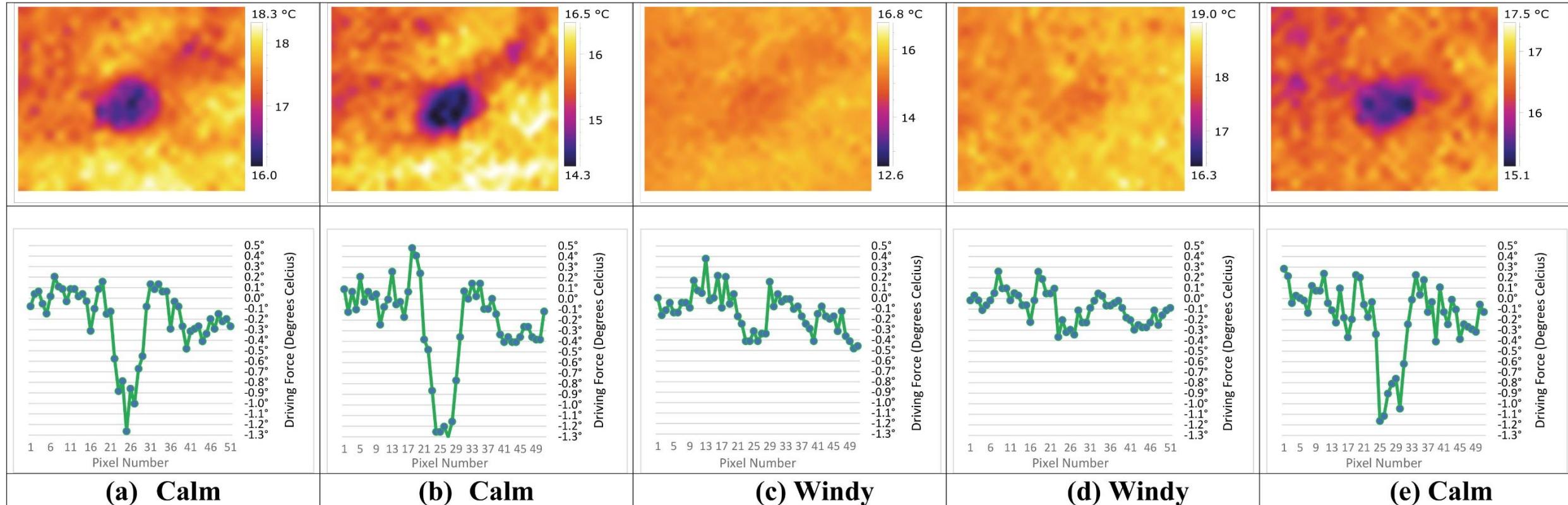
# 9. Lessons Learned - TIR

## Diurnal cycle



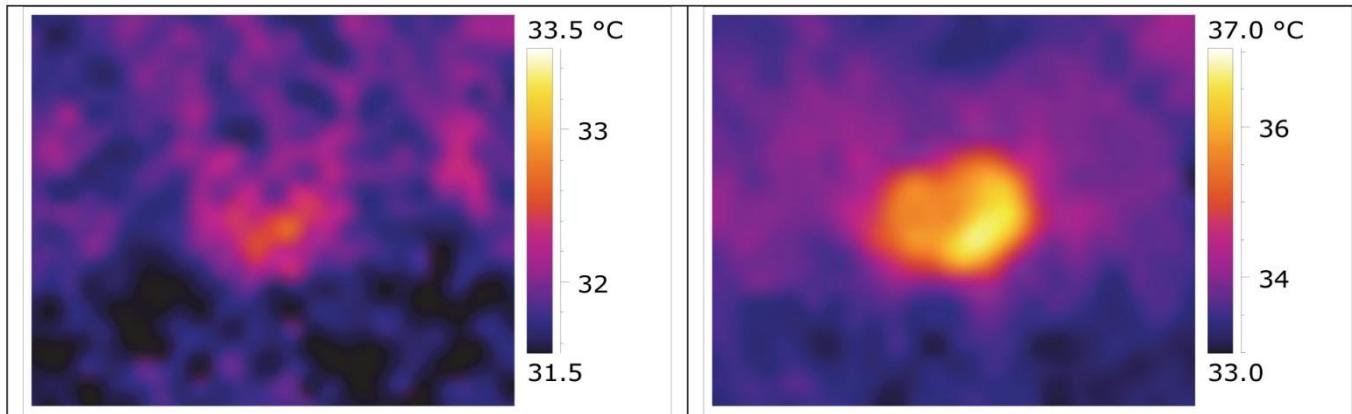
# 9. Lessons Learned - TIR

## Wind



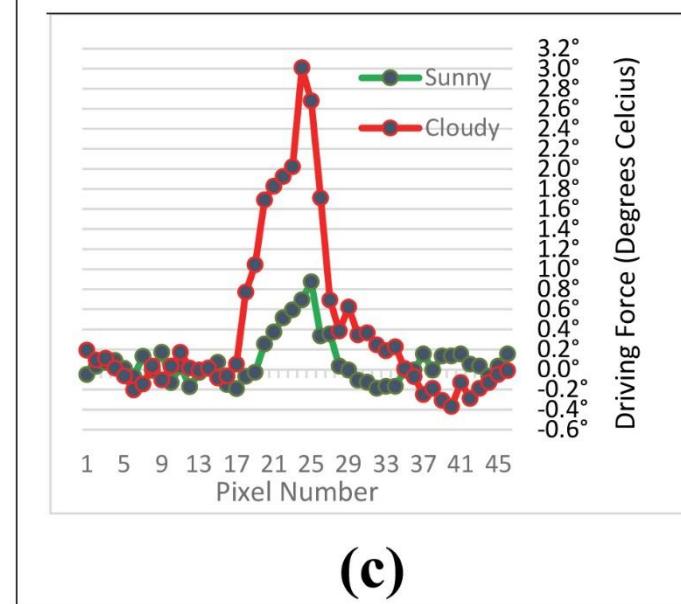
# 9. Lessons Learned - TIR

## Cloud



(a)

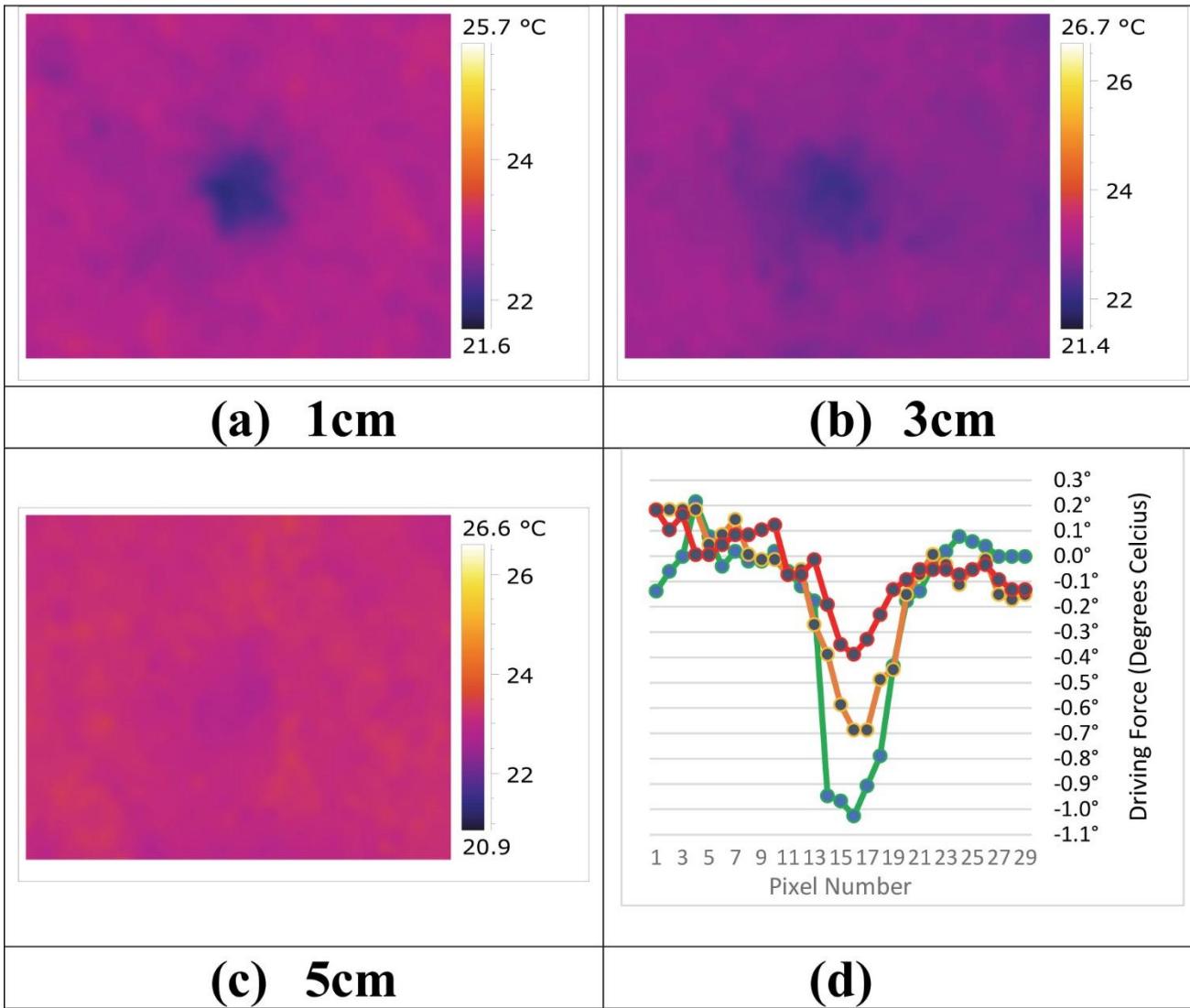
(b)



(c)

# 9. Lessons Learned - TIR

## Depth



## 10. Validating Results

# Validation (deminers)



# Thanks & Questions



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